

RESPUESTAS CINEMÁTICA DE LA PARTÍCULA

En las expresiones cinemáticas de velocidades y de aceleraciones el subíndice 1 indica el marco tierra.

Los vectores unitarios $\{\hat{i}, \hat{j}\}$ indicados en las soluciones corresponden a los sentidos horizontal hacia la derecha y vertical hacia arriba respectivamente y además los vectores $\{\hat{p}, \hat{q}\}$ definen otra base ortogonal en el plano.

1.- a) $\bar{V}_1^P = 8\hat{i} + 16\hat{j}$; $\bar{a}_1^P = 8\hat{i} + 16\hat{j}$ b) $y = 2x - 6$ c) $s(t) = 4\sqrt{5}(2t + t^2)$

2.- $\bar{V}_1^P = \frac{8}{3}\pi\hat{i}$ (m/s) ; $\bar{a}_1^P = \frac{8}{3}\pi\hat{i} - \frac{16}{9}\pi^2\hat{j}$ (m/s²)

3.- $\bar{a}_1^A = 2bv^2\hat{j}$ (m/s²)

4.- a) $r = r_0 e^{\theta}$; b) $|\bar{a}_1^P| = \frac{2r_0^2 v_0^2}{r^3}$

5.- a) $|\bar{a}_{1t}^P| = \frac{26}{\sqrt{29}}$; b) $\rho = \frac{29\sqrt{29}}{\sqrt{165}}$

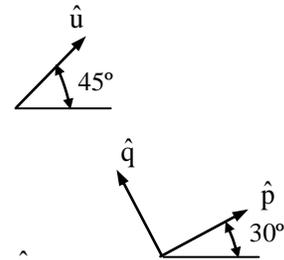
6.- $|\bar{V}_1^A| = \sqrt{\frac{2(2L-d)b}{Ld}}$

7.- a) $x^2 + \left(y - \frac{v}{\omega}\right)^2 = \left(\frac{v}{\omega}\right)^2$; b) $\rho = \frac{v}{\omega}$; c) $|\bar{a}_{1n}^P| = \omega v$

9.- $\bar{V}_1^P = 4,03\hat{i} - 16,5\hat{j}$ (m/s) ; t = 0,71 (s)

10.- $\bar{V}_1^P = -\frac{\pi R}{2}\hat{i}$; $\bar{a}_1^P = -\frac{\pi R}{4}\hat{i} - \frac{\pi^2 R}{4}\hat{j}$
 $\bar{V}_2^P = -\frac{\sqrt{2}}{4}\pi R\hat{u}$; $\bar{a}_2^P = -\frac{\pi R\sqrt{2}}{16}(2+\pi)\hat{u}$

donde 2 es la barra



11.- $\bar{V}_1^{C2} = v\hat{i} + \frac{1}{2}v\hat{q}$; $\bar{a}_1^{C2} = -\frac{1}{8h}v^2\hat{p} + \frac{\sqrt{3}}{12h}v^2\hat{q}$

donde 2 es la barra

12.- $\bar{V}_1^P = -\sqrt{2}v\hat{i}$; $\bar{a}_1^P = \frac{1}{R}v^2\hat{i} + \frac{2}{R}v^2\hat{j}$

$$13.- \quad \bar{a}_1^P = \frac{v^2}{(1+x^2)^2} (-x \hat{i} + \hat{j})$$

$$14.- \quad \bar{a}_1^P = \frac{v^2 (2+\theta^2)}{3(1+\theta^2)^2} [-\theta \hat{e}_r + \hat{e}_\theta]$$

$$15.- \quad \begin{array}{l} \text{En } \theta = 0, \quad \bar{V}_1^P = 2b\omega \hat{j} \\ \text{En } \theta = \pi, \quad \bar{V}_1^P = \bar{0} \end{array} \quad ; \quad \begin{array}{l} \text{En } \theta = \frac{\pi}{2}, \quad \bar{V}_1^P = -b\omega \hat{i} - b\omega \hat{j} \\ \text{En } \theta = -\frac{\pi}{2}, \quad \bar{V}_1^P = b\omega \hat{i} - b\omega \hat{j} \end{array}$$

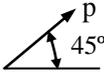
$$16.- \quad \bar{V}_1^{B3} = v \hat{j} \quad ; \quad \bar{a}_1^{B3} = -\frac{2\sqrt{2}}{R} v^2 \hat{j}$$

donde 3 es la barra

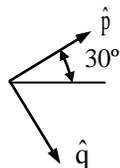
$$17.- \quad \bar{V}_1^P = -\frac{1}{2} v \hat{i} - v \hat{j} \quad (\text{m/s}) \quad ; \quad \bar{a}_1^P = -\frac{1}{20} v^2 \hat{i} \quad (\text{m/s}^2)$$

$$\bar{V}_2^P = -\frac{1}{2} v \hat{i} \quad (\text{m/s}) \quad ; \quad \bar{a}_2^P = -\frac{1}{20} v^2 \hat{i} \quad (\text{m/s}^2)$$

donde 2 es la pieza

$$18.- \quad \bar{V}_2^P = -\frac{\sqrt{2}}{2} v \hat{p} \quad ; \quad \bar{a}_2^P = \frac{\sqrt{2}}{4b} v^2 \hat{p}$$


donde 2 es la barra

$$19.- \quad \text{a) } \dot{\beta} = \frac{1}{R} v \quad ; \quad \text{b) } \bar{a}_2^A = \frac{2\sqrt{3}}{R} v^2 \hat{p} + \frac{4}{R} v^2 \hat{q}$$


$$20.- \quad \bar{V}_1^A = \sqrt{2} v \hat{i} \quad ; \quad \bar{a}_1^A = \frac{1}{b} v^2 \hat{i}$$

$$21.- \quad \bar{V}_1^P = \bar{0} \quad ; \quad \bar{a}_1^P = -\frac{L}{4} \omega^2 \hat{i} + \frac{L\sqrt{3}}{2} \omega^2 \hat{j}$$

$$\bar{V}_2^P = \frac{L\sqrt{3}}{2} \omega \hat{i} \quad ; \quad \bar{a}_2^P = -\frac{L}{4} \omega^2 \hat{i}$$

donde 2 es la pieza triangular

$$22.- \quad \bar{V}_1^P = \sqrt{2\pi b R} (\sqrt{2} - 1) \hat{i}$$

$$\bar{a}_1^P = 2Rb \hat{i} - 2(3 - 2\sqrt{2})\pi b R \hat{j}$$

23.- $|\bar{a}_{1t}^P| = 0$

24.- $s = b \omega t$

25.- b) $|\bar{a}_{1r}^P| = \frac{3v^2}{4b}$

26.- a) $\bar{a}_1^P = -\sqrt[3]{\frac{Lb^2}{3}} \hat{j}$; b) $\bar{a}_1^P = \left[\frac{Lb^2}{6}(3+\pi) \right]^{\frac{1}{3}} \hat{i} + \frac{b^2}{288L} \left[\frac{36L}{b}(3+\pi) \right]^{\frac{4}{3}} \hat{j}$

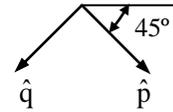
27.- $\bar{V}_1^{C2} = -\sqrt{2}v \hat{i}$; $\bar{a}_1^{C2} = -\frac{1}{R}v^2 \hat{i} + \frac{2}{R}v^2 \hat{j}$

donde 2 es la barra

28.- $\bar{V}_1^P = \frac{3}{4}\pi R \hat{p}$; $\bar{a}_1^P = \frac{1}{2}\pi R \hat{p} + \frac{27}{48}\pi^2 R \hat{q}$

$\bar{V}_2^P = -\frac{3\sqrt{2}\pi R}{8} \hat{j}$; $\bar{a}_2^P = -\frac{\sqrt{2}\pi R}{32}(8+9\pi) \hat{j}$

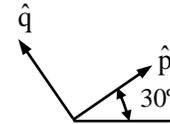
donde 2 es la pieza



29.- $\bar{V}_1^A = \frac{\sqrt{3}}{2}v \hat{p}$; $\bar{a}_1^A = \bar{0}$

$\bar{V}_2^A = \frac{1}{2}v \hat{q}$; $\bar{a}_2^A = \bar{0}$

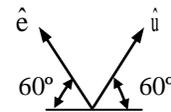
donde 2 es el brazo



30.- $\bar{V}_1^P = \frac{2\pi}{3} \hat{i} + \frac{2\sqrt{3}\pi}{3} \hat{j}$ (m/s)

31.- $\bar{V}_1^P = \frac{\sqrt{3}}{3}v \hat{e}$; $\bar{V}_2^P = -\frac{\sqrt{3}}{3}v \hat{u}$

donde 2 es el aro



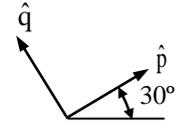
32.- $\rho = \frac{2\sqrt{2}(1+\cos\omega t)b}{3}$

33.- a) $y = h - \frac{g}{2} \sqrt[3]{\left(\frac{3x}{\omega g \cos \lambda} \right)^2}$; b) $\delta = \frac{2\omega h \cos \lambda}{3} \sqrt{\frac{2h}{g}}$

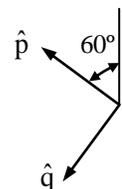
35.- $\bar{V}_1^P = \sqrt{3}R \omega \hat{j}$; $\bar{a}_1^P = 3R \omega^2 \hat{i} - \frac{R}{2}\omega^2 \hat{j}$

36.- $\bar{V}_1^A = \sqrt{2} v \hat{i} \quad ; \quad \bar{a}_1^A = -\frac{1}{R} v^2 \hat{i} - \frac{2}{R} v^2 \hat{j}$

37.- $\bar{V}_1^{B2} = -v \hat{i} - \frac{2\sqrt{3}}{3} v \hat{q} \quad ; \quad \bar{a}_1^{B2} = \frac{v^2}{9R} (-3 \hat{p} + 7\sqrt{3} \hat{q})$
 donde 2 es la barra



38.- $\bar{V}_1^P = \left(\frac{\sqrt{3}}{2} L \omega + v \right) \hat{p} + \frac{L}{2} \omega \hat{q}$
 $\bar{a}_1^P = -\frac{3L}{4} \omega^2 \hat{p} + \omega [2v + L\sqrt{3}\omega] \hat{q}$



39.- $\bar{V}_1^C = \bar{0} \quad ; \quad \bar{a}_1^C = 2\omega^2 L \hat{j}$

40.- $\bar{V}_1^P = -0,35v \hat{i} + 0,53v \hat{j} \quad (\text{m/s})$

41.- $\bar{a}_1^P = R \omega^2 \hat{p} + \left(L - \frac{R\pi}{4} \right) \omega^2 \hat{q}$



42.- a) $|\bar{a}_{1t}^P| = b \omega^2 r_o \sqrt{1+b^2} e^{b\omega t} \quad ; \quad |\bar{a}_{1n}^P| = r_o \omega^2 \sqrt{1+b^2} e^{b\omega t}$

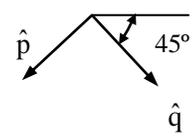
b) $\rho = r_o \sqrt{1+b^2} e^{b\omega t}$

43.- $r(t) = \frac{\sqrt{2}}{2} [vt + \sqrt{2} r_o] \quad ; \quad \theta(t) = \text{Ln} \left[\frac{\sqrt{2} v}{2 r_o} t + 1 \right]$

44.- $|\bar{a}_{1r}^P| = \frac{8\lambda^2 r_o^2}{r^5} \quad ; \quad \text{donde } \lambda \text{ es constante}$

45.- $\bar{a}_1^A = -\frac{b^4}{a^2 y^3} v^2 \hat{j}$

46.- $\bar{V}_1^A = \frac{\pi R}{4} \hat{p} \quad ; \quad \bar{a}_1^A = \frac{\pi R}{8} \hat{p} + \frac{\pi^2 R}{16} \hat{q}$



47.- $\bar{V}_1^C = -\sqrt{2} v \hat{i} \quad ; \quad \bar{a}_1^C = \frac{1}{R} v^2 \hat{i} - \frac{2}{R} v^2 \hat{j}$

48.- $\vec{V}_1^A = 2v \hat{j}$; $\vec{a}_1^A = \vec{0}$
 $\vec{V}_2^A = v \hat{j}$; $\vec{a}_2^A = \vec{0}$
 donde 2 es la pieza

49.- a) $x^2 + y^2 = \left(\frac{L}{2}\right)^2$; b) $\vec{V}_1^{C2} = \frac{1}{2}v \hat{i} - \frac{1}{2}v \hat{j}$
 donde 2 es la barra y C su punto medio

51.- a) $t = \sqrt{\frac{1}{2b}}$; b) $\vec{V}_1^{P'} = -0,47 \sqrt{b} R \hat{j}$

52.- $R = 12$ (m)

53.- $s = 8b$

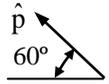
54.- a) $\vec{V}_1^A = \frac{v\sqrt{1+4x^2}}{(1+8x^2)} (\hat{i} + 4x\hat{j})$; b) $\dot{\phi} = \frac{2v}{(1+8x^2)\sqrt{1+4x^2}}$; c) $\vec{a}_2^A = \vec{0}$
 donde 2 es la varilla OB

55.- $\vec{V}_1^P = \frac{R}{2} \cos\left(\frac{1}{4}\right) \hat{j}$; $\vec{a}_1^P = \frac{R}{16} \left(4 \cos\left(\frac{1}{4}\right) - \text{sen}\left(\frac{1}{4}\right) \right) \hat{j}$

56.- a) $\vec{V}_1^P = \vec{0}$; $\vec{a}_1^P = -\frac{v^2}{R} \hat{i}$

b) $\vec{V}_2^P = v \hat{j}$; $\vec{a}_2^P = -\frac{v^2}{R} \hat{i}$
 donde 2 es el aro

57.- $t = \frac{\pi}{2} \sqrt{\frac{R}{a}}$

58.- a) $\vec{V}_1^B = \frac{2\sqrt{3}}{3} v \hat{p}$  b) $\dot{\theta} = \frac{2\sqrt{3}}{3L} v$

59.- $\dot{\theta} = -\frac{4\sqrt{3}}{9}$ (rad/s) ; $\ddot{\theta} = -\frac{64\sqrt{3}}{81}$ (rad/s²)

60.- $\vec{V}_1^E = \frac{25}{3} \hat{j}$ (m/s) ; $\vec{a}_1^E = \frac{400}{27} \hat{j}$ (m/s²)